

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S37	17	"5710498"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:08
S38	2	"20060186845"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:17
S39	1555	(318/432).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/21 15:51
S40	55	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:54
S41	55	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:20
S42	26	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:21

S43	10	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:22
S44	1555	(318/432).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:11
S45	10	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:11
S46	9	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat \$4 subtract\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:17

S47	9	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat\$4 subtract\$4) and (position\$4 near9 (correct\$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum\$4 summation) same (differenc\$4 error deviat\$4 subtract\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:19
S48	4	((("5371361") or ("5790692"))).PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:21
S49	2	("20080024085").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:32
S51	295	"318"/\$7.ccls. and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat\$4 subtract\$4) and (position\$4 near9 (correct\$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:34
S52	259	"318"/\$7.ccls. and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat\$4 subtract\$4) and (position\$4 near9 (correct\$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum\$4 summation) same (differenc\$4 error deviat\$4 subtract\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:37

S53	80	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat \$4 subtract\$4)) and ((filter\$4 lpf hpf) same gain\$4 same (differenc \$4 error deviat\$4 subtract \$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:40
S54	66	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat \$4 subtract\$4)) and ((filter\$4 lpf hpf) same gain\$4 same (differenc \$4 error deviat\$4 subtract \$4)) and (torque same (speed velocity))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:41

S55	53	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat \$4 subtract\$4)) and ((filter\$4 lpf hpf) same gain\$4 same (differenc \$4 error deviat\$4 subtract \$4)) and ((torque same (speed velocity)) same position\$4)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:43
S56	47	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) near9 (differenc\$4 error deviat \$4)) and ((filter\$4 lpf hpf) same gain\$4 same (differenc\$4 error deviat \$4 subtract\$4)) and ((torque same (speed velocity)) same position \$4)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:45
S57	2	("6054827").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 17:48

10/24/2009 5:24:29 PM

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